




# FRANCESCO BANELLI

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## EDUCATION

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### ETH Zurich

MSc in Robotics, Systems and Control

*Relevant coursework: Probabilistic AI, Deep Generative Models, Perception and Learning*

*Sept 2024 –Present*

GPA: 5.83/6.0

### Politecnico di Milano

BSc in Automation and Control Engineering

Graduation Grade: 110/110 cum Laude

*Sept 2021 –Jul 2024*

GPA: 29.35/30

## RESEARCH AND WORK EXPERIENCE

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### AI Engineering Intern, Flexion Robotics - Perception Team

*Mar 2026 –Present*

- Developing a learned proprioceptive state estimation module to complement an existing classical localization and mapping pipeline.
- Training generative models in NVIDIA Isaac Lab on the Unitree G1 for robot perception and state estimation and deployment on the real robot.

### Research Assistant, ETH Zurich - Raffaello D'Andrea's group

*Feb 2025 –Feb 2026*

- Designed high-throughput GPU-based pipeline using Dense Inverse Search (DIS) for optical flow estimation, achieving 2 kHz inference speed using JAX, 16× faster than OpenCV baseline.
- Built a synthetic data generator for PIV exceeding 10k frames/s, enabling large-scale supervised training and benchmarking; > 1000× faster than PIVlab.
- Developed a reinforcement-learning-based algorithm selection policy, reducing flow estimation error by 33% vs. best baseline.

## PUBLICATIONS AND SELECTED PROJECTS

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### Flow Gym

Francesco Banelli, Antonio Terpin, Alan Bonomi, Raffaello D'Andrea

*SoftwareX, accepted*

### SynthPix: A lightspeed PIV image generator

Antonio Terpin, Alan Bonomi, Francesco Banelli, Raffaello D'Andrea

*SoftwareX, accepted*

### PIV Refinement via Consensus ADMM

Alan Bonomi, Francesco Banelli, Antonio Terpin

*Under review at CDC 2026*

### Learned Acceleration Estimator

*Sept 2023 –Dec 2023*

- Trained a neural estimator to predict drone accelerations from command sequences, replacing IMU sensors in the state estimation pipeline.

## TECHNICAL SKILLS

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**Core ML:** PyTorch, JAX/Flax, Reinforcement Learning, Deep Generative Models

**Vision & Estimation:** Optical Flow, VIO, Kalman Filters, State Observers, Sensor Fusion

**Programming:** Python, C/C++, MATLAB, Bash